

# Exploiting the Structure of Two Graphs via Graph Neural Networks

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## Introduction

### Problem formulation

#### Numerical Results

### Connections with CCA and SSL

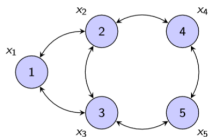
#### Numerical Results

## Conclusions

- ▶ Each day huge amounts of data are generated
  - ⇒ **Irregular** structure
- ▶ Need to find new ways to
  - ⇒ Represent the data
  - ⇒ Learn from it

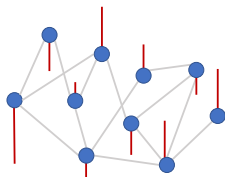


- ▶ Representation of irregular data
  - ⇒ Via more complex structures → **graphs**
- ▶ Learning over irregular data
  - ⇒ New machine learning algorithms
- ▶ Join both in **graph neural networks (GNNs)**

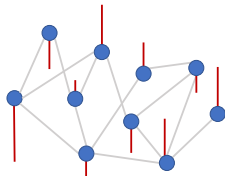


- ▶ **This work:** input and output are defined over different graphs

- ▶ A **graph**  $\mathcal{G}$ :  $N$  nodes and links connecting them
  - $\Rightarrow \mathcal{G} \equiv (\mathcal{V}, \mathcal{E}, \mathbf{A})$
  - $\Rightarrow \mathcal{V} = \{1, \dots, N\}, \mathcal{E} \subseteq \mathcal{V} \times \mathcal{V}, \mathbf{A} \in \mathbb{R}^{N \times N}$
- ▶ Define a signal  $\mathbf{x} \in \mathbb{R}^N$  on top of the graph
  - $\Rightarrow x_i =$  Signal value at node  $i$



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- ▶ Associated with  $\mathcal{G} \rightarrow$  graph-shift operator (GSO)  $\mathbf{S} \in \mathbb{R}^{N \times N}$ 
  - $\Rightarrow S_{ij} \neq 0$  if and only if  $i = j$  or  $(i, j) \in \mathcal{E}$  (local structure in  $\mathcal{G}$ )
- ▶ **Graph Signal Processing**  $\rightarrow$  Exploit structure encoded in  $\mathbf{S}$  to process  $\mathbf{x}$
- ▶ First **linear processing**: graph filters, graph Fourier transform...
- ▶ Then **neural nets**: GCNNs, GRNNs, G-Tensor, G-Autoencoders



- ▶ Existing NN works dealing with **graph signals** [Bruna17]
  - ⇒ Input graph signal  $\mathcal{G}$ , output scalar (class)
  - ⇒ Input graph signal  $\mathcal{G}$ , output graph signal  $\mathcal{G}$  (embeddings)

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  - ▶  $\mathcal{G}_X$  with  $N$  nodes (signal  $\mathbf{x} \in \mathbb{R}^N$ ), and graph-shift operator  $\mathbf{S}_X$
  - ▶  $\mathcal{G}_Y$  with  $M$  nodes (signal  $\mathbf{y} \in \mathbb{R}^M$ ), and graph-shift operator  $\mathbf{S}_Y$

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- ▶ **Goal:** Learn the **nonlinear mapping**  $f_{\Theta} : \mathbb{R}^N \rightarrow \mathbb{R}^M$

$$\mathbf{y} = f_{\Theta}(\mathbf{x} | \mathcal{G}_X, \mathcal{G}_Y)$$

exploiting  $\mathcal{G}_X$  and  $\mathcal{G}_Y$  and using a Neural Network (NN) architecture



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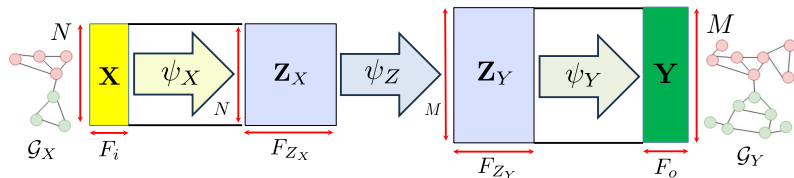
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- ▶ **Key:** Consider **latent space  $\mathbf{Z}$**  to transform between graphs

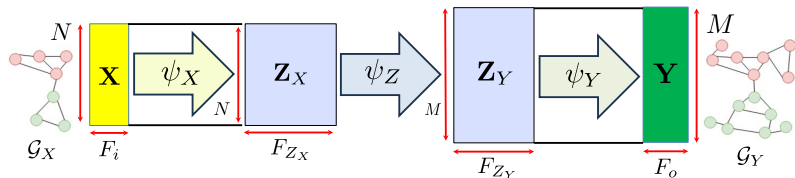
- ▶ The underlying space  $\mathbf{Z}$  implies that

$$\mathbf{x} \text{ on } \mathcal{G}_X \xRightarrow{\underbrace{\psi_{\Theta_X}^X}} \mathbf{z}_X \in \mathbb{R}^{N \times F_{Z_X}}, \quad \mathbf{z}_X \xRightarrow{\underbrace{\psi_{\Theta_Z}^Z}} \mathbf{z}_Y \in \mathbb{R}^{M \times F_{Z_Y}}, \quad \mathbf{z}_Y \xRightarrow{\underbrace{\psi_{\Theta_Y}^Y}} \mathbf{y} \text{ on } \mathcal{G}_Y$$



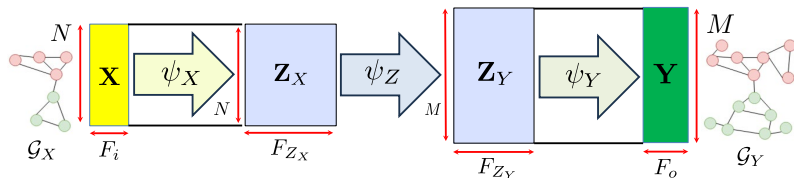
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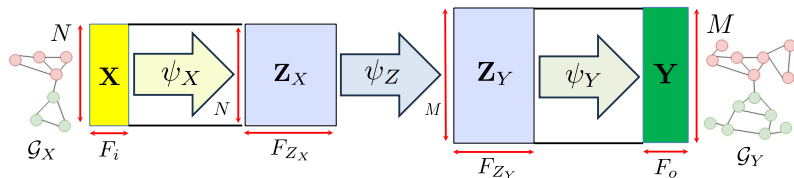
- ▶ More precisely

- $\Rightarrow \psi_{\Theta_X}^X$  standard GNN operating over  $\mathcal{G}_X$
- $\Rightarrow \psi_{\Theta_Y}^Y$  standard GNN operating over  $\mathcal{G}_Y$
- $\Rightarrow \psi_{\Theta_Z}^Z$  transformation between domains: design covered later



- The input-output mapping is then

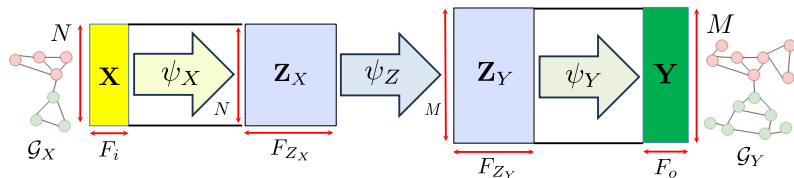
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- ▶ Parameters  $\Theta_X$ ,  $\Theta_Y$  and (possibly)  $\Theta_Z$ 
  - ⇒ Learned through backpropagation
  - ⇒ Assumption:  $\psi_{\Theta_Z}^Z$  is differentiable

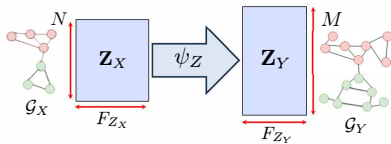


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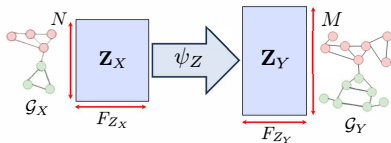
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- ▶ Key in this approach: design of  $\psi_{\Theta_Z}^Z$

- Several design decisions  $\rightarrow$  taxonomy

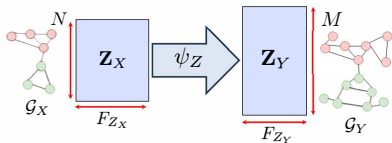


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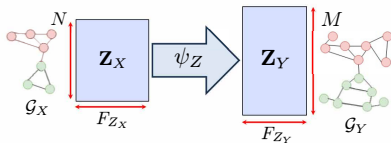




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  - $\Rightarrow$  Propose a parametric function with parameters  $\Theta_Z$
  - $\Rightarrow$   $\Theta_Z$  learned through gradient descent and backpropagation



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- ▶ Learnable vs fixed in advance  
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- ▶ Linear vs more complex transformations  
 $\Rightarrow$  Most general case of linear transformation

$$\text{vec}(\mathbf{Z}_Y) = \mathbf{W}\text{vec}(\mathbf{Z}_X),$$

- $\Rightarrow$  With (possibly learnable) transformation  $\mathbf{W} \in \mathbb{R}^{MF_{Z_Y} \times NF_{Z_X}}$
- $\Rightarrow$  Huge number of parameters if graphs are large  $\rightarrow$  overfitting
- $\Rightarrow$  Can incorporate structure to the transformation
- $\Rightarrow$  More complex can include e.g. MLP

- ▶ Low Rank  $\mathbf{W} = \mathbf{W}_Y \mathbf{W}_X^T$ 
  - ⇒  $\mathbf{W}_Y \in \mathbb{R}^{MF_{Z_Y} \times K}$  and  $\mathbf{W}_X \in \mathbb{R}^{NF_{Z_X} \times K}$
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  - ⇒ Using property  $\text{vec}(\mathbf{ABC}) = (\mathbf{C}^T \otimes \mathbf{A})\text{vec}(\mathbf{B})$

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  - ⇒  $\mathbf{W}_N \in \mathbb{R}^{M \times N}$  combines information across nodes
  - ⇒  $\mathbf{W}_F \in \mathbb{R}^{F_{Z_X} \times F_{Z_Y}}$  combines information across features
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- ▶ Permutation matrix
  - ⇒ Cells in  $\mathbf{Z}_X$  are rearranged to form  $\mathbf{Z}_Y$

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  - ⇒ Example of  $\mathbf{W}$  as a permutation matrix
  - ⇒ Non-learnable
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- ▶  $\mathbf{Z}_Y = \mathbf{W}_N \mathbf{Z}_X$ 
  - ⇒ Simple Kronecker structure with  $\mathbf{W}_F = \mathbf{I}$
  - ⇒  $F_{Z_X} = F_{Z_Y}$
  - ⇒  $\mathbf{W}_N$  learned through backpropagation

- ▶ Standard GNNs are **permutation equivariant**

$$\psi(\mathbf{P}\mathbf{X}, \mathbf{P}\mathbf{S}\mathbf{P}^T) = \mathbf{P}\psi(\mathbf{X}, \mathbf{S})$$

⇒ For any permutation matrix  $\mathbf{P} \in \mathbb{R}^{N \times N}$

- ▶ Can we say the same about IOGNN?
  - ⇒ Input and output are not defined on the same space
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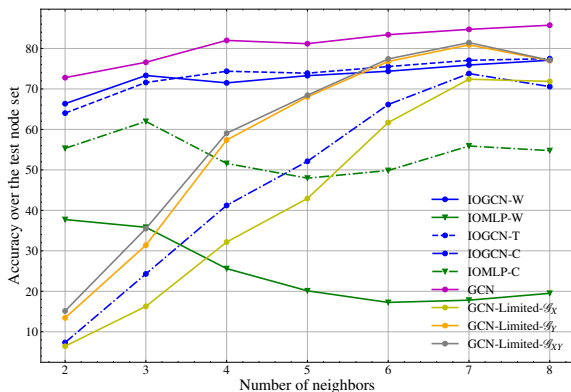
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- ▶ As an example, consider the transformation  $\mathbf{Z}_Y = \mathbf{W}_N \mathbf{Z}_X$

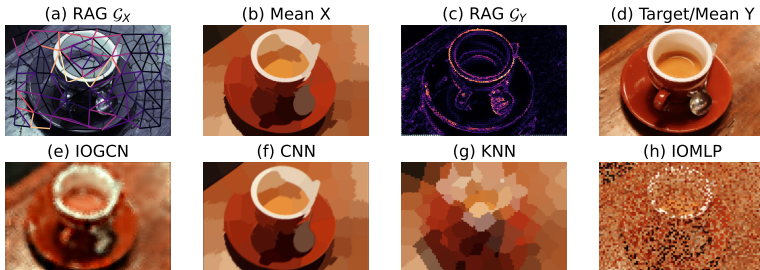
⇒ Rearrange weight matrix as  $\mathbf{W}'_N = \mathbf{P}_Y \mathbf{W}_N \mathbf{P}_X^T$

- ▶ From a graph  $\mathcal{G}$  we sample two subgraphs  $\mathcal{G}_X$  and  $\mathcal{G}_Y$ 
  - ⇒  $\mathcal{G}$  is the Cora graph
  - ⇒ Mapping from node features in  $\mathcal{G}_X$  to labels in  $\mathcal{G}_Y$

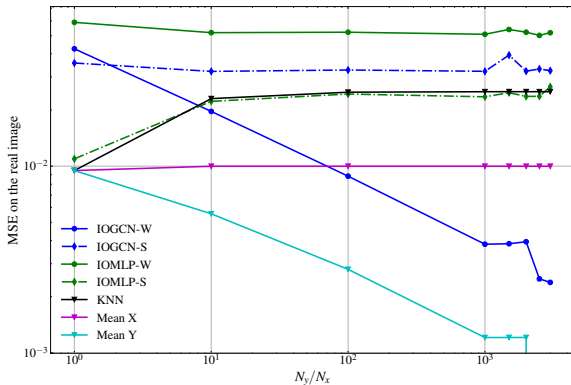


- ▶ Framework suited for the interpolation task
  - ⇒  $\mathcal{G}_X$  is a coarse/subgraph of  $\mathcal{G}_Y$
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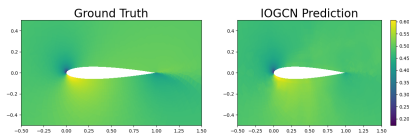
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- ▶ Interpolation in the field of CFD
  - ⇒ Solved via Navier-Stokes PDE on meshes
  - ⇒ Fine meshes are computationally costly
  
- ▶ Fully supervised setting

	Interpolation	Generalization
CFD-GCN*	1,8e-02	5,4e-02
GCN*	1,4e-02	9,5e-02
IOGCN-W	<b>6,7e-03</b>	4,1e-02
IOGCN-S	1,7e-02	<b>3,7e-02</b>
IOGAT-W	8,7e-03	6,6e-02
IOGAT-S	8,3e-03	6,2e-02
IOMLP-W	8,4e-03	4,0e-02
GAT	1,1e-02	1,1e-01



► Canonical Correlation Analysis (CCA)

⇒ Given two views of data  $\mathbf{X} \in \mathbb{R}^{N \times F_X}$  and  $\mathbf{Y} \in \mathbb{R}^{N \times F_Y}$

⇒ Compute transformations  $\mathbf{U} \in \mathbb{R}^{F_X \times F_Z}$  and  $\mathbf{V} \in \mathbb{R}^{F_Y \times F_Z}$

⇒ Seek maximal correlation in transformed space

$$\max_{\mathbf{U}, \mathbf{V}} \text{tr}(\mathbf{U}^T \boldsymbol{\Sigma}_{XY} \mathbf{V})$$

$$\text{s. to: } \mathbf{U}^T \boldsymbol{\Sigma}_{XX} \mathbf{U} = \mathbf{V}^T \boldsymbol{\Sigma}_{YY} \mathbf{V} = \mathbf{I},$$

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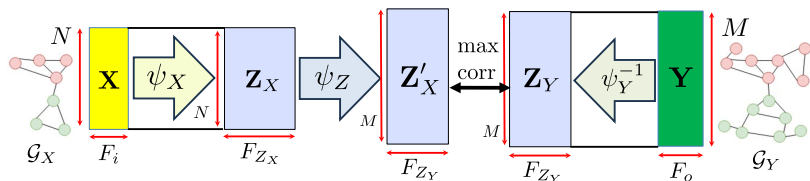
$$\max_{\boldsymbol{\Theta}_X, \boldsymbol{\Theta}_Y} \text{tr}(f_{\boldsymbol{\Theta}_X}(\mathbf{X})^T f_{\boldsymbol{\Theta}_Y}(\mathbf{Y}))$$

$$\text{s. to: } f_{\boldsymbol{\Theta}_X}(\mathbf{X})^T f_{\boldsymbol{\Theta}_X}(\mathbf{X}) = f_{\boldsymbol{\Theta}_Y}(\mathbf{Y})^T f_{\boldsymbol{\Theta}_Y}(\mathbf{Y}) = \mathbf{I}$$

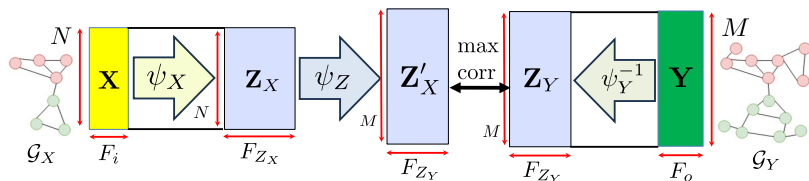
⇒ Slight different reformulation (CCA-SSG)

$$\min_{\boldsymbol{\Theta}_X, \boldsymbol{\Theta}_Y} \|f_{\boldsymbol{\Theta}_X}(\mathbf{X}) - f_{\boldsymbol{\Theta}_Y}(\mathbf{Y})\|_F^2 + \lambda (\mathcal{L}_{SDL}(f_{\boldsymbol{\Theta}_X}(\mathbf{X})) + \mathcal{L}_{SDL}(f_{\boldsymbol{\Theta}_Y}(\mathbf{Y})))$$

- ▶ We can apply our architecture to the CCA setting
  - ⇒ Now we know both  $\mathbf{X}$  and  $\mathbf{Y}$
  - ⇒ Goal: find alternative representations  $\mathbf{Z}_X$  and  $\mathbf{Z}_Y$



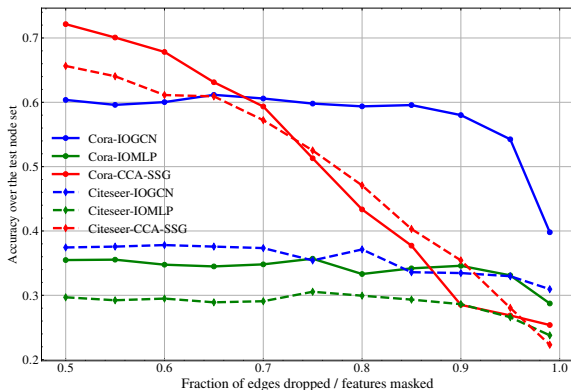
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- ▶ Aim to solve

$$\begin{aligned} & \max_{\Theta_X, \Theta_Z, \Theta_Y} \text{tr}(\psi_{\Theta_Z}^Z(\psi_{\Theta_X}^X(\mathbf{X}|\mathcal{G}_X))^T \psi_{\Theta_Y}^Y^{-1}(\mathbf{Y}|\mathcal{G}_Y)) \\ & \text{s. to: } \psi_{\Theta_Z}^Z(\psi_{\Theta_X}^X(\mathbf{X}|\mathcal{G}_X))^T \psi_{\Theta_Z}^Z(\psi_{\Theta_X}^X(\mathbf{X}|\mathcal{G}_X)) = \\ & \quad \psi_{\Theta_Y}^Y^{-1}(\mathbf{Y}|\mathcal{G}_Y)^T \psi_{\Theta_Y}^Y^{-1}(\mathbf{Y}|\mathcal{G}_Y) = \mathbf{I} \end{aligned}$$

- ▶ Problem setting
  - ⇒  $\mathcal{G}$  is a common graph with two views
  - ⇒  $\mathcal{G}_X$  edges dropped, features masked
  - ⇒  $\mathcal{G}_Y$  subgraph with perfect information
- ▶ Perform node classification via transformed views
  - ⇒ SSL setting



- ▶ Novel NN architecture to learn mapping from  $(\mathbf{x}, \mathcal{G}_X)$  to  $(\mathbf{y}, \mathcal{G}_Y)$
- ▶ **Key idea:** latent common space and two graph-aware NN
  - ⇒ Step 1) graph-aware NN from  $(\mathbf{x}, \mathcal{G}_X)$  to latent space  $\mathbf{Z}_X$
  - ⇒ Step 2) transformation between  $\mathbf{Z}_X$  in  $\mathcal{G}_X$  to  $\mathbf{Z}_Y$  in  $\mathcal{G}_Y$
  - ⇒ Step 3) graph-aware NN from latent space  $\mathbf{Z}_Y$  to  $(\mathbf{y}, \mathcal{G}_Y)$
  - ⇒ Parameters jointly learned (backpropag using input-output pairs)



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  - ⇒ Flexible design to accommodate different scenarios

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- ▶ Taxonomy of functions for transformation  $\psi_Z$ 
  - ⇒ Several design decisions
  - ⇒ Flexible design to accommodate different scenarios
- ▶ Analogies with CCA and SSL
  - ⇒ Able to learn alternative informative representations
  - ⇒ Used for downstream tasks

# Thank you



Thank  
You

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