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Graph Topology Identification Based on Covariance Matching

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Graph Topology Identification

Understanding Hidden Relationships

In many fields, relationships among entities are not directly observable. Graph topology identification helps to infer these hidden structures from nodal data.





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Graph Topology Identification (GTT)

General Process

- GTI relies on the fact that the nodal data is related to the graph.
- Specifically, it follows a distribution determined by the graph

 $\mathbf{x} \sim \mathscr{F}(\mathbf{S}).$

• This could be the Gaussian distribution:

 $\mathscr{F}(\mathbf{S}) = \mathcal{N}(\boldsymbol{\mu}(\mathbf{S}), \boldsymbol{\Sigma}(\mathbf{S})).$

• Here, both $\mu(S)$ and $\Sigma(S)$ are functions of the graph structure S.

Approaches

- Smoothness of data over graph
- Graphical Lasso
- Spectral template
- Structural equation model (SEM)

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Structural	Equation Model	(SEM)		

Setup

• We consider graph signals **x** following the model:

$$\mathbf{x} = \mathbf{S}\mathbf{x} + \mathbf{e}, \quad \mathbf{x} = (\mathbf{I} - \mathbf{S})^{-1}\mathbf{e}.$$

• We assume that **S** represents the *adjacency matrix* of an *undirected* graph with N nodes, implying

$$\mathbf{S} = \mathbf{S}^{\top}, \quad \text{diag}(\mathbf{S}) = \mathbf{0}.$$

• We further assume the exogenous variables satisfy

 $\mathbf{e} \sim \mathcal{N}(\mathbf{0}, \mathbf{I}).$

• This overall leads to the following distribution for **x**:

$$\mathbf{x} \sim \mathcal{N}\left(\mathbf{0}, \ (\mathbf{I}-\mathbf{S})^{-2}\right)$$

• Observing *T* realizations, we collect them into the data matrix

$$\mathbf{X} = [\mathbf{x}_1, \ldots, \mathbf{x}_T].$$

	Signal Matching		
Linear R	egression		

Optimization Problem

• **SigMatch** seeks \hat{S} by minimizing:

$$\min_{\hat{\mathbf{S}}} \|\mathbf{X} - \hat{\mathbf{S}} \mathbf{X}\|_F^2 \quad \text{subject to} \quad \hat{\mathbf{S}} = \hat{\mathbf{S}}^\top, \text{ diag}(\hat{\mathbf{S}}) = \mathbf{0}.$$

- Not the maximum likelihood estimator!
- Only good approach for:
 - A directed acyclic graph (DAG)
 - Deterministic known exogenous variables

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Analysis of	SigMatch			



Convergence Issue

We can prove that, for *any* underlying graph shift matrix **S**, the linear regression method **fails** to converge to the correct graph even for $T \to \infty$.

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Covariance I	Matching			

Covariance Matching Framework

• Goal: Estimate S so that the theoretical covariance

$$\Sigma_x = (\mathbf{I} - \mathbf{S})^{-2}$$

is close to the *sample* covariance

$$\mathbf{C}_{\mathbf{X}} = \frac{1}{T} \mathbf{X} \mathbf{X}^{\top}.$$

- Why? Close to the true maximum likelihood.
- Optimization problem:

$$\mathbf{S}^* = \arg\min_{\hat{\mathbf{S}}} \left\| \mathbf{C}_{\mathbf{X}} - (\mathbf{I} - \hat{\mathbf{S}})^{-2} \right\|_F$$
 subject to $\hat{\mathbf{S}} = \hat{\mathbf{S}}^\top$, diag $(\hat{\mathbf{S}}) = \mathbf{0}$

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Solution	Approach			

Spectral Template Idea

• Take the EVD

$$\mathbf{C}_{\mathbf{X}} = \mathbf{U}_{\mathbf{X}} \operatorname{diag}(\lambda_{\mathbf{X}}) \mathbf{U}_{\mathbf{X}}^{\top},$$

and model

$$(\mathbf{I} - \hat{\mathbf{S}})^{-1} = \hat{\mathbf{U}} \operatorname{diag}(\hat{\lambda}) \hat{\mathbf{U}}^{\top}$$

which means

$$(\mathbf{I} - \hat{\mathbf{S}})^{-2} = \hat{\mathbf{U}} \operatorname{diag}(\hat{\boldsymbol{\lambda}}^2) \hat{\mathbf{U}}^{\mathsf{T}}$$

• Key Idea:

- Rather than solving directly for $\hat{\mathbf{S}}$, we *estimate* $\hat{\mathbf{U}}$ and $\hat{\boldsymbol{\lambda}}$.
- By choosing $\hat{\mathbf{U}} = \mathbf{U}_{\mathbf{x}}$, this task reduces to fitting $\hat{\lambda}^2$ to $\lambda_{\mathbf{x}}$.
- The constraint to guarantee is diag $((\mathbf{I} \hat{\mathbf{S}})) = \text{diag}(\hat{\mathbf{U}} \text{ diag}(\hat{\lambda}^{-1}) \hat{\mathbf{U}}^{\top}) = \mathbf{1}.$

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Optimization Formulation

Swapping the objective and the constraint

• The resulting optimization problem becomes:

$$\lambda^* = \arg\min_{\hat{\lambda}} \|\hat{\lambda}^2 - \lambda_{\mathbf{x}}\|_2^2 \quad \text{subject to} \quad \operatorname{diag}(\mathbf{U}_{\mathbf{x}} \operatorname{diag}(\hat{\lambda}^{-1}) \mathbf{U}_{\mathbf{x}}^{\top}) = \mathbf{1}.$$

• Alternatively, we can swap the objective and constraint

- We enforce λ² = λ_x as a constraint.
 We fit diag(U_x diag(λ⁻¹) U_x^T) as close as possible to 1.
- This results in the following problem

$$\lambda^* = \arg\min_{\hat{\lambda}} \quad \|\operatorname{diag}(\mathbf{U}_{\mathbf{x}}\operatorname{diag}(\hat{\lambda}^{-1})\mathbf{U}_{\mathbf{x}}^{\top}) - \mathbf{1}\|_2^2 \quad \text{subject to} \quad \hat{\lambda}^2 = \lambda_{\mathbf{x}}.$$

Addressing Sign Ambiguity and Final Optimization

Sign Ambiguity

- Note that $\hat{\lambda}^2 = \lambda_{\mathbf{x}}$, introduces a sign ambiguity for $\hat{\lambda}$.
- Denoting the sign vector as $\hat{\mathbf{q}} \in \{-1, 1\}^N$, the constraint $\hat{\lambda}^2 = \lambda_{\mathbf{x}}$ can be rewritten as

$$\hat{\lambda} = \operatorname{diag}(\hat{\mathbf{q}}) \lambda_{\mathbf{x}}^{1/2}.$$

• The objective function can then be written as

$$\|\operatorname{diag}(\mathbf{U}_{\mathbf{x}}\operatorname{diag}(\hat{\mathbf{q}})\operatorname{diag}(\lambda_{\mathbf{x}}^{-1/2})\mathbf{U}_{\mathbf{x}}^{\top}) - \mathbf{1}\|_{2}^{2} = \|\left(\mathbf{U}_{\mathbf{x}}\odot\mathbf{U}_{\mathbf{x}}\right)\operatorname{diag}(\lambda_{\mathbf{x}}^{-1/2})\hat{\mathbf{q}} - \mathbf{1}\|_{2}^{2}$$

Final Problem

• Putting this all together and defining $W = (U_x \odot U_x) \operatorname{diag}(\lambda_x^{-1/2})$, the final problem becomes a binary quadratic programming problem

$$\mathbf{q}^* = \arg \min_{\hat{\mathbf{q}} \in \{-1,1\}^N} \|\mathbf{W}\hat{\mathbf{q}} - \mathbf{1}\|_2^2.$$

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Results and Observations

Settings

- Graph with 20 nodes and 20 edges
- 100 graph realizations
- Simple: $\mathbf{U} \odot \mathbf{U}$ high rank
- Hard: $U \odot U$ low rank



Key Observations

- SpecTemp does not exploit SEM structure and has problems with rank loss
- SigMatch never converges, but shows better performance with fewer samples.
- CovMatch maintains robust performance across both simple and hard scenarios.

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Polynomia	al Model			

Motivation and Model

• The SEM model can be seen as a special case of a more general *polynomial model* with

$$h(\mathbf{S}) = (\mathbf{I} - \mathbf{S})^{-1}.$$

• We consider graph signals:

$$\mathbf{x} = h(\mathbf{S}) \mathbf{e}, \qquad h(\mathbf{S}) = \sum_{\ell=0}^{L-1} h_{\ell} \mathbf{S}^{\ell}.$$

- We again assume $\mathbf{S} = \mathbf{S}^{\top}$, diag(\mathbf{S}) = 0, and $\mathbf{e} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$.
- Then the covariance of **x** is

$$\mathbf{x} \sim \mathcal{N}(\mathbf{0}, h^2(\mathbf{S})).$$

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Covariance Matching for Polynomial Models

Key Steps

• We wish to match

$$\mathbf{C}_{\mathbf{x}} \approx h^2(\hat{\mathbf{S}}).$$

• Assuming now that $\hat{\mathbf{S}} = \hat{\mathbf{U}} \operatorname{diag}(\hat{\lambda}) \hat{\mathbf{U}}^{\top}$, we have

$$h(\hat{\mathbf{S}}) = \hat{\mathbf{U}} \operatorname{diag}(h(\hat{\lambda})) \hat{\mathbf{U}}^{\top}$$

- Setting $\hat{\mathbf{U}} = \mathbf{U}_{\mathbf{X}}$ (from the EVD of $\mathbf{C}_{\mathbf{X}}$) as before, we need to match $h^2(\hat{\lambda})$ to $\lambda_{\mathbf{X}}$ (from the EVD of $\mathbf{C}_{\mathbf{X}}$).
- This matching is turned into a constraint, leading to a set of polynomial equations

$$h^2(\hat{\lambda}_i) = \lambda_{i,\mathbf{x}}, \quad i = 1, \dots, N.$$

• The constraint $\text{diag}(\hat{S}) = 0$ is on the other hand turned into the objective

$$\|\operatorname{diag}(\mathbf{U}_{\mathbf{x}} \operatorname{diag}(\hat{\lambda}) \mathbf{U}_{\mathbf{x}}^{\top})\| = \|(\mathbf{U}_{\mathbf{x}} \odot \mathbf{U}_{\mathbf{x}}) \hat{\lambda}\|_{2}^{2}.$$

	Polynomial Model	

Optimization Formulation

Final Form

- Let $\lambda_{i,\mathbf{x}}$ be the *i*-th eigenvalue of $\mathbf{C}_{\mathbf{x}}$.
- Then each scalar constraint $h^2(\hat{\lambda}_i) = \lambda_{i,\mathbf{x}}$ has a (finite) set of roots $\{\tilde{c}_i^1, \ldots, \tilde{c}_i^{p_i}\}$.
- All this put together leads to the following problem

$$\min_{\hat{\lambda}} \| (\mathbf{U}_{\mathbf{X}} \odot \mathbf{U}_{\mathbf{X}}) \, \hat{\lambda} \|_{2}^{2} \quad \text{subject to} \quad \hat{\lambda}_{i} \in \{ \tilde{c}_{i}^{1}, \dots, \tilde{c}_{i}^{p_{i}} \}.$$

• This is a discrete optimization problem.

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SEM with C	Colored Exoger	nous Variables		

Setup

- So far, we assumed $\mathbf{e} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$.
- In many settings, **e** can be Gaussian with a *known*, *non*-identity covariance:

 $\mathbf{e} \sim \mathcal{N}(\mathbf{0}, \Sigma_{\mathbf{e}}), \quad \Sigma_{\mathbf{e}} \neq \mathbf{I}.$

• Since the SEM is given by $\mathbf{x} = (\mathbf{I} - \mathbf{S})^{-1} \mathbf{e}$, this leads to

$$\boldsymbol{\Sigma}_{\boldsymbol{X}} = \mathbb{E}\{\boldsymbol{x}\boldsymbol{x}^{\top}\} = (\boldsymbol{I} - \boldsymbol{S})^{-1} \boldsymbol{\Sigma}_{\boldsymbol{e}} (\boldsymbol{I} - \boldsymbol{S})^{-\top}.$$

• Defining $\mathbf{H} = (\mathbf{I} - \mathbf{S})^{-1}$, then results in the following matching problem

 $\hat{H} \Sigma_e \, \hat{H}^\top \approx C_x.$

• Key Idea: Instead of matching $\hat{H}\,\Sigma_e\,\hat{H}^{\top}\approx C_x,$ we match

$$(\hat{\mathbf{H}} \boldsymbol{\Sigma}_{\mathbf{e}})^2 \approx \mathbf{C}_{\mathbf{x}} \boldsymbol{\Sigma}_{\mathbf{e}}.$$

- Results in a structure where an unknown square has to be matched to something we know
- This now involves the EVD of $C_{x} \Sigma_{e}$.

Covariance Matching for Colored Exogenous Variables

Final Optimization

- As discussed we need to match $(\hat{H} \Sigma_e)^2 \approx C_x \Sigma_e$.
- For the right hand side we obtain the EVD

$$\mathbf{C}_{\mathbf{x}} \, \boldsymbol{\Sigma}_{\mathbf{e}} = \mathbf{U}_{\mathbf{x}\mathbf{e}} \, \operatorname{diag}(\boldsymbol{\lambda}_{\mathbf{x}\mathbf{e}}) \, \mathbf{U}_{\mathbf{x}\mathbf{e}}^{-1}.$$

• For the left hand side, we use the model

$$\hat{\mathbf{H}} \Sigma_{\mathbf{e}} = \hat{\mathbf{U}} \operatorname{diag}(\hat{\lambda}) \hat{\mathbf{U}}^{-1}, \quad (\hat{\mathbf{H}} \Sigma_{\mathbf{e}})^2 = \hat{\mathbf{U}} \operatorname{diag}(\hat{\lambda}^2) \hat{\mathbf{U}}^{-1}.$$

- We set $\hat{\mathbf{U}} = \mathbf{U}_{\mathbf{xe}}$ and define a sign vector $\hat{\mathbf{q}} \in \{-1, 1\}^N$ satisfying $\hat{\lambda} = \operatorname{diag}(\hat{\mathbf{q}})\lambda_{\mathbf{xe}}^{1/2}$.
- $\bullet\,$ The hollow constraint on \hat{S} again leads to a binary quadratic programming problem:

$$\min_{\hat{\mathbf{q}}} \big\| \big((\boldsymbol{\Sigma}_{e} \ \mathbf{U}_{xe}) \odot \mathbf{U}_{xe}^{-\top} \big) \operatorname{diag}(\boldsymbol{\lambda}_{xe}^{-1/2}) \ \hat{\mathbf{q}} \ - \ \mathbf{1} \big\|_{2}^{2}.$$

		Colored Distribution
Experiments		



Settings

- Positive and negative edge weights
- For SEM, colored exogenous variables
 - Sparse: 20 nodes and 20 edges with rank loss
 - Fully connected: 20 nodes with all edges; no particular attention to rank
- For polynomial model, white exogenous variables and filter order 3

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Conclusio	ons and Future W	ork		

Conclusions

• We introduced a covariance matching approach for a SEM on undirected graphs in white noise.

• Key advantages:

- Close to maximum likelihood estimation.
- No scale ambiguities and convergence issues.
- We extended the approach to **polynomial models** and a **colored** exogenous variables.

Future Work

- Incorporating **sparsity priors** or advanced regularizers for large-scale graphs.
- Exploring this method for directed acyclic graphs
- Exploring dynamic or time-varying topologies with evolving network structures.

		Colored Distribution
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Thank you for your attention!

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